

Effects of Particle Deposition Profile on L \rightarrow H Transition and Hysteresis Dynamics

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Outline

- L-- H transitions and hysteresis in 1D, phase coexistence
- **Continuous media 1D model**
 - Transition point selection in a steady state:
 - regularization
 - time dependence, functional approach
 - Scan of parameter space
 - Pressure curvature (second derivative) effects
- ☐ Internal fueling
- ☐ Time dependent fueling
- **0-D, ODE-model, time dependent case**
 - Fixed point analysis, bifurcations
 - Hysteresis, transition control
- Conclusions

Simple two-field model of L-H transition

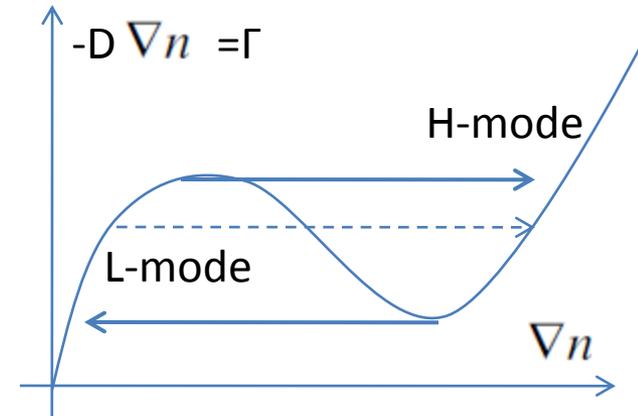
(Hinton, Staebler '93)

Particle transport with fueling S

$$\frac{\partial n}{\partial t} - \frac{\partial}{\partial x} \left[D_0 + \frac{D_1}{1 + \alpha V_E'^2} \right] \frac{\partial n}{\partial x} = S(x)$$

Neoclassical diffusion

Turbulent part



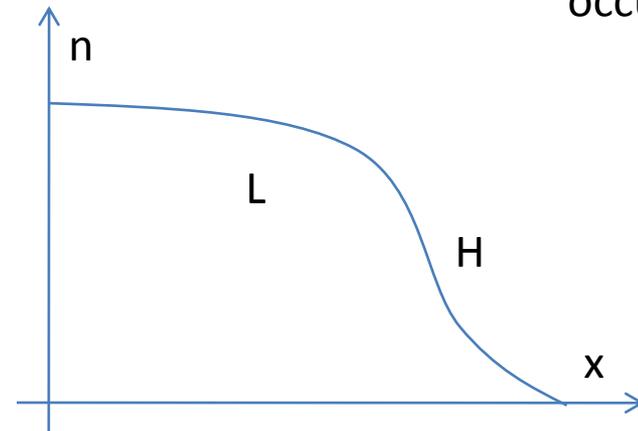
Heat transport, source H

$$\frac{3}{2} \frac{\partial p}{\partial t} - \frac{\partial}{\partial x} \left[\chi_0 + \frac{\chi_1}{1 + \alpha V_E'^2} \right] \frac{\partial p}{\partial x} = H(x)$$

Suppression: $\mathbf{E} \times \mathbf{B}$ flow shear

$$V_E' \simeq \frac{c}{eB} \frac{\partial}{\partial x} n^{-1}(x) \frac{\partial}{\partial x} p(x)$$

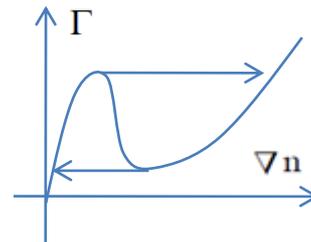
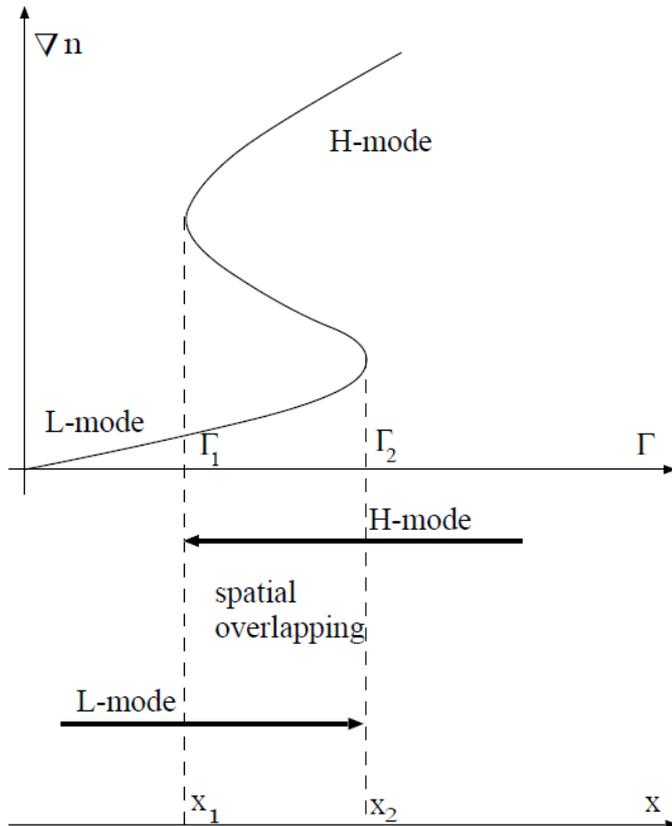
Pedestal parameters depend on where exactly transition occurs



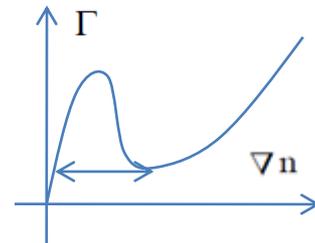
Phase coexistence dilemma

The problem can be considered as
Propagation of one phase into another

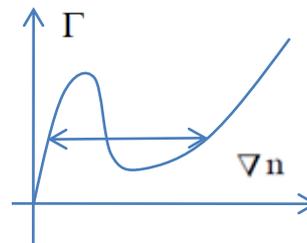
selection of transition point



Stay at a stable branch
As long as it exists
(works in 0D)



Minimum gradient jump
Criterion
Hinton and Staebler '93



Maxwell (equal area)
Rule: works in 1D, 1
field (n) model
Lebedev and Diamond
'95

Phase-coexistence conditions in a steady state

$$D_0 g_1 + \frac{D_1 g_1}{1 + \alpha V_E'^2} = \int_0^x S(x) dx \equiv \Gamma_s(x) \quad g_1 = -\frac{\partial n}{\partial x},$$

$$\chi_0 g_2 + \frac{\chi_1 g_2}{1 + \alpha V_E'^2} = \int_0^x H(x) dx \equiv Q_s(x) \quad g_2 = -\frac{\partial p}{\partial x}.$$

Algebraic problem for one of the gradients:

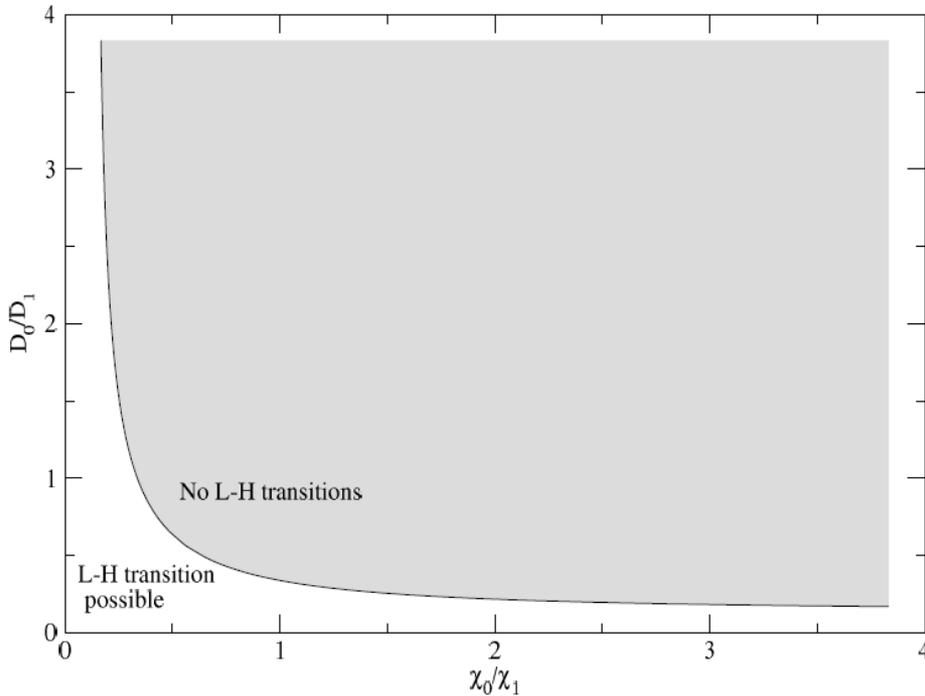
$$g + \frac{\lambda g}{1 + g^4 (1 + \Theta g)^{-2}} = \hat{\Gamma}$$

$$\hat{\Gamma} = K D_0^{-1} \sqrt{Q_s \Gamma_s(x) D_1 / \chi_1}; \quad \lambda = D_1 / D_0$$

$$\Theta = K^{-1} \sqrt{\chi_1 D_1 / Q_s \Gamma_s(x)} (\chi_0 / \chi_1 - D_0 / D_1) \quad K = \alpha^{1/4} \sqrt{c / e B n}^{-1}.$$

➤ model predicts a close link between fueling depth and the width of the enhanced confinement region

Phase-coexistence criteria and the depth of the bifurcation in a steady state



Bifurcation depth defined as

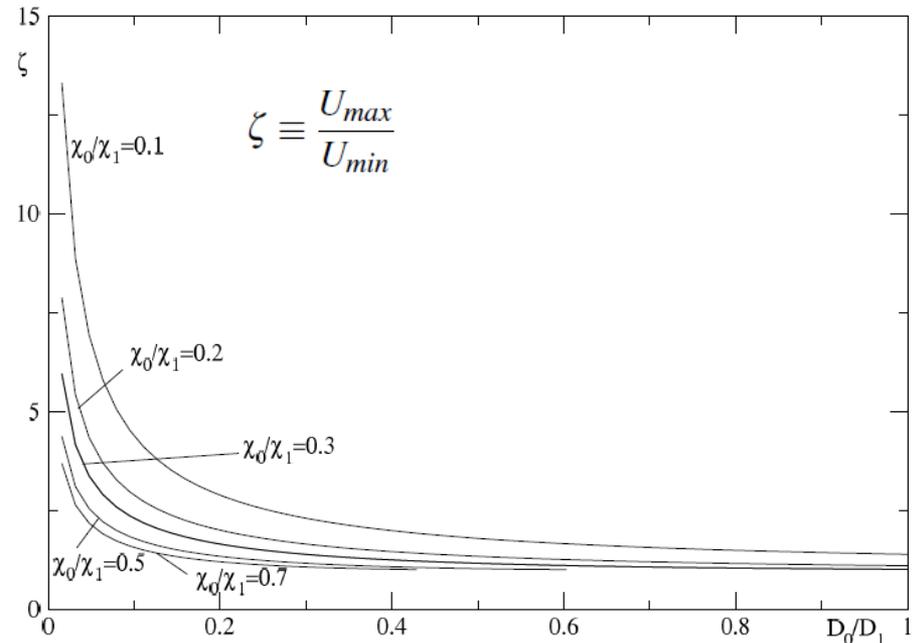
$$\zeta \equiv \frac{U_{max}}{U_{min}}$$

Neoclassical to turbulent transport
Ratio parameter space

Phase coexistence range

$$U_{min} < K^2 \frac{\Gamma_s Q_s}{D_0 \chi_0} < U_{max}$$

$$K^2 = \sqrt{\alpha c} / e B n^2$$



Hyperdiffusion Regularization

$$\Phi'(g) - \Gamma_s(x) - \varepsilon^2 \frac{\partial^2 g}{\partial x^2} = 0 \quad \longrightarrow \quad \text{Maxwell rule}$$

Time dependent regularization

$$\chi_{0,1} \gg D_{0,1} \quad \frac{\partial g}{\partial t} = \frac{\partial^2}{\partial x^2} \frac{\delta \Lambda}{\delta g} \quad \Lambda = \int_0^a [\Phi(g) - \Gamma_s g] dx$$

$$\frac{d\Lambda}{dt} = - \int_0^a \left\{ \frac{\partial}{\partial x} [\Phi'(g) - \Gamma_s] \right\}^2 dx \leq 0$$

Minimum Λ \longrightarrow Maxwell rule

- Maxwell rule governs forward and back transitions
- hysteresis is absent

Curvature of the pressure profile

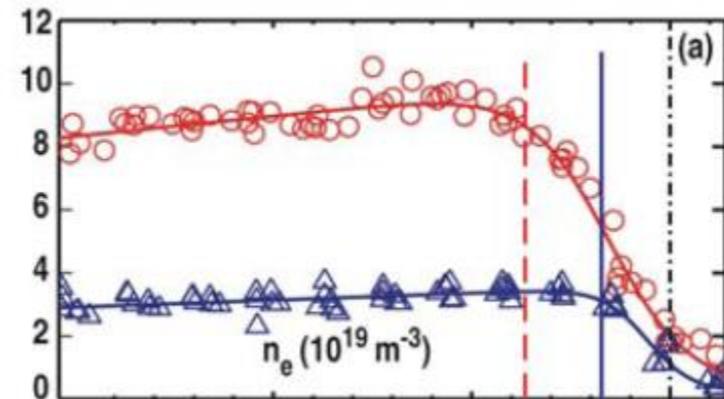
$$\frac{\partial V_E}{\partial x} \simeq -\frac{c}{eBn^2} \frac{\partial n}{\partial x} \frac{\partial p}{\partial x} + \frac{c}{eBn} \frac{\partial^2 p}{\partial x^2}$$

$$g_2 + \frac{(\beta - 1) g_2}{1 + \left(\frac{\sigma g_2^2}{1 + \kappa g_2} + \mu \frac{dg_2}{dx} \right)^2} = q(x)$$

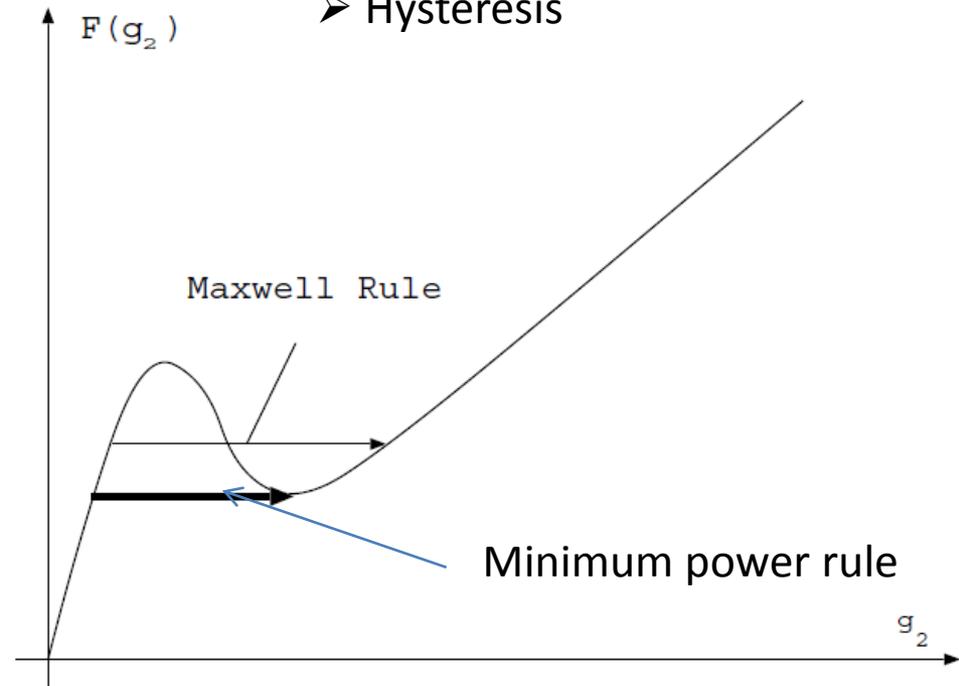
Second derivative resolves transition location

Differential equation for the pressure gradient
Instead of algebraic one

- Likely scenario: Maxwell forward
- Minimum power back transition
- Hysteresis



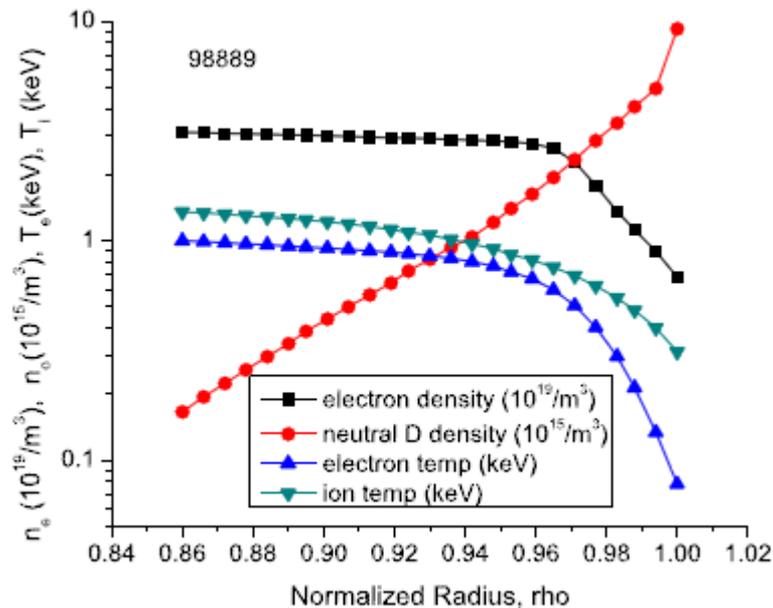
R.J. Groebner et al '09



Notations

$$q = Q_s / \chi_0, \quad \beta = 1 + \chi_1 / \chi_0,$$

$$\sigma = \sqrt{\alpha} \frac{c}{eBn^2} \frac{\Gamma_s \chi_1}{Q_s D_1}; \quad \kappa = \frac{D_0 \chi_1 - \chi_0 D_1}{D_1 Q_s}; \quad \mu = \sqrt{\alpha} \frac{c}{eBn} \equiv nK^2$$



- Second derivative of pressure is clearly important, as opposed to that of the density profile

- Model correctly captures the roles of density and pressure profiles in suppressing the fluxes

Internal deposition at a finite depth within the separatrix (SMBI)

Phase transition

$$F(g) \equiv g + \frac{(\beta - 1)g}{1 + v^2 g^4 (1 + kg)^{-2}} = 1$$

$$g = \frac{\chi_0}{Q_s} g_2 \quad v = \frac{\sqrt{\alpha} c}{e B n^2} \frac{\Gamma_s \chi_1}{\chi_0^2 D_1} Q_s \quad k = \frac{D_0 \chi_1}{D_1 \chi_0} - 1$$

$kg < 1$ -reasonable approximation on the ground of a better pronounced density LH transition compared to the pressure (temperature) transition

Phase transition threshold

$$\frac{\sqrt{\alpha} c}{e B n^2} \frac{\Gamma_s Q_s}{\chi_0 D_1} > \frac{16}{3^{3/2}} \sqrt{\frac{\chi_0}{\chi_1}}$$

Heating power may be reduces at the fueling expense

- However, density build up requires more deposition and heating

Barrier propagation for time dependent deposition

$$\frac{\partial g}{\partial t} = \frac{\partial^2}{\partial x^2} [F(g) - \Gamma(x, t)]$$

F-nonlinear particle flux, Γ -internal deposition (integrated in x)

Let the barrier at $x=b(t)$

$$g(x, t) = \begin{cases} g^+, & x \geq b(t) \\ g^-, & x < b(t) \end{cases}$$

$$\frac{\partial g}{\partial t} - \dot{b} \frac{\partial g}{\partial \xi} = \frac{\partial^2}{\partial \xi^2} [f - \Gamma(x + b)] \quad \xi = \tilde{x} - \dot{b}(t).$$

Barrier propagates according to

$$\dot{b} = \frac{a(f_b - \Gamma_b) - b(f_a - \Gamma_a)}{\Delta g b (a - b)}$$

Inward barrier propagation promoted by

- under-fueling at the wall
- over-fueling at the barrier

Time dependent 0-D model

$$\frac{d\mathcal{E}}{d\tau} = (\mathcal{N} - a_1\mathcal{E} - a_2d^2\mathcal{N}^4 - a_3V_{ZF}^2) \mathcal{E}$$

DW generation by temperature
Gradient N, NL saturation and by
By mean and zonal flows

$$\frac{dV_{ZF}}{d\tau} = \left(\frac{b_1\mathcal{E}}{1 + b_2d^2\mathcal{N}^4} - b_3 \right) V_{ZF}$$

ZF generation by Reynolds stress
Suppression by mean flow and
Damping by collisions

$$\frac{d\mathcal{N}}{d\tau} = -(c_1\mathcal{E} + c_2)\mathcal{N} + q(\tau)$$

Temperature gradient maintained by
Heat source q and relaxed by turbulent and
Neoclassical transport

Mean flow

$$V = d\mathcal{N}^2$$

(Kim and Diamond '03)

- System demonstrated interesting behavior including dithering
- System has too many parameters
- Difficult to classify dynamics

Reduction to a five-parameter system

$$\frac{dE}{dt} = (N - N^4 - E - U) E$$

$$\frac{dU}{dt} = \vartheta \left(\frac{E}{1 + \zeta N^4} - \eta \right) U$$

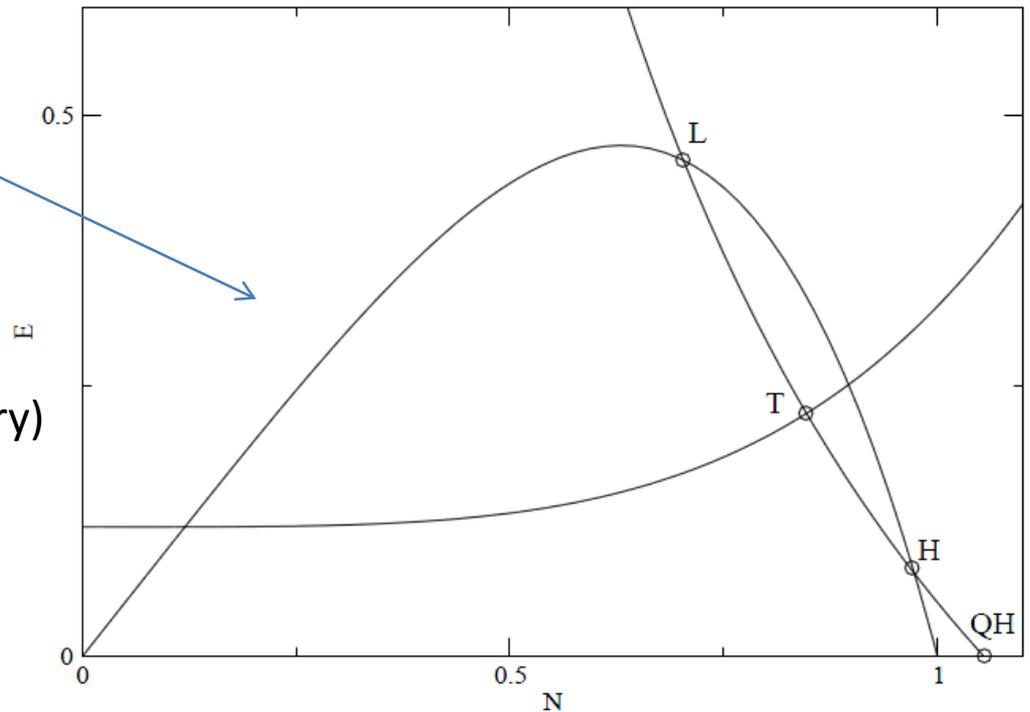
$$\frac{dN}{dt} = q(t) - (\rho + \sigma E) N$$

- Dynamics is limited to a set of 2D manifolds around fixed points (Center manifolds)

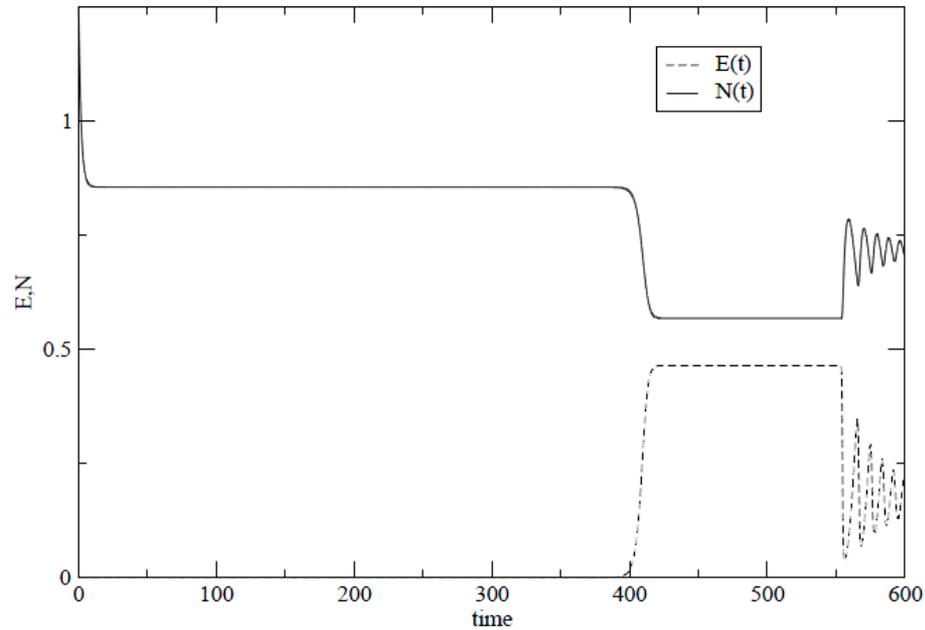
U=0 plane (no ZF) projection
Of the fixed points

q increases
↓

- L-mode
- T-mode (transient oscillatory)
- H-mode
- QH- quiescent H mode



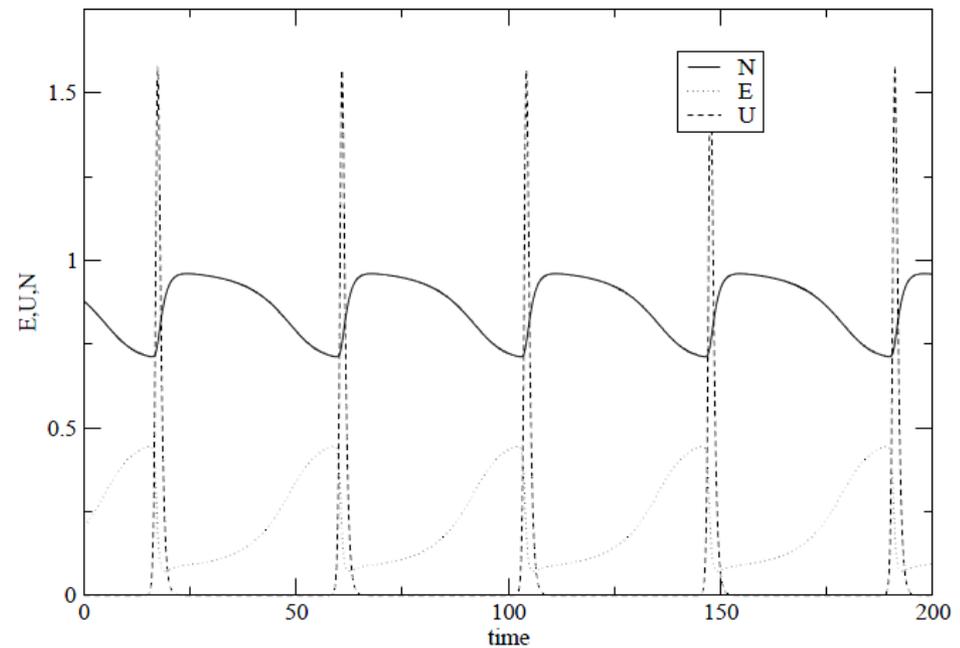
Meta-stable states and transitions



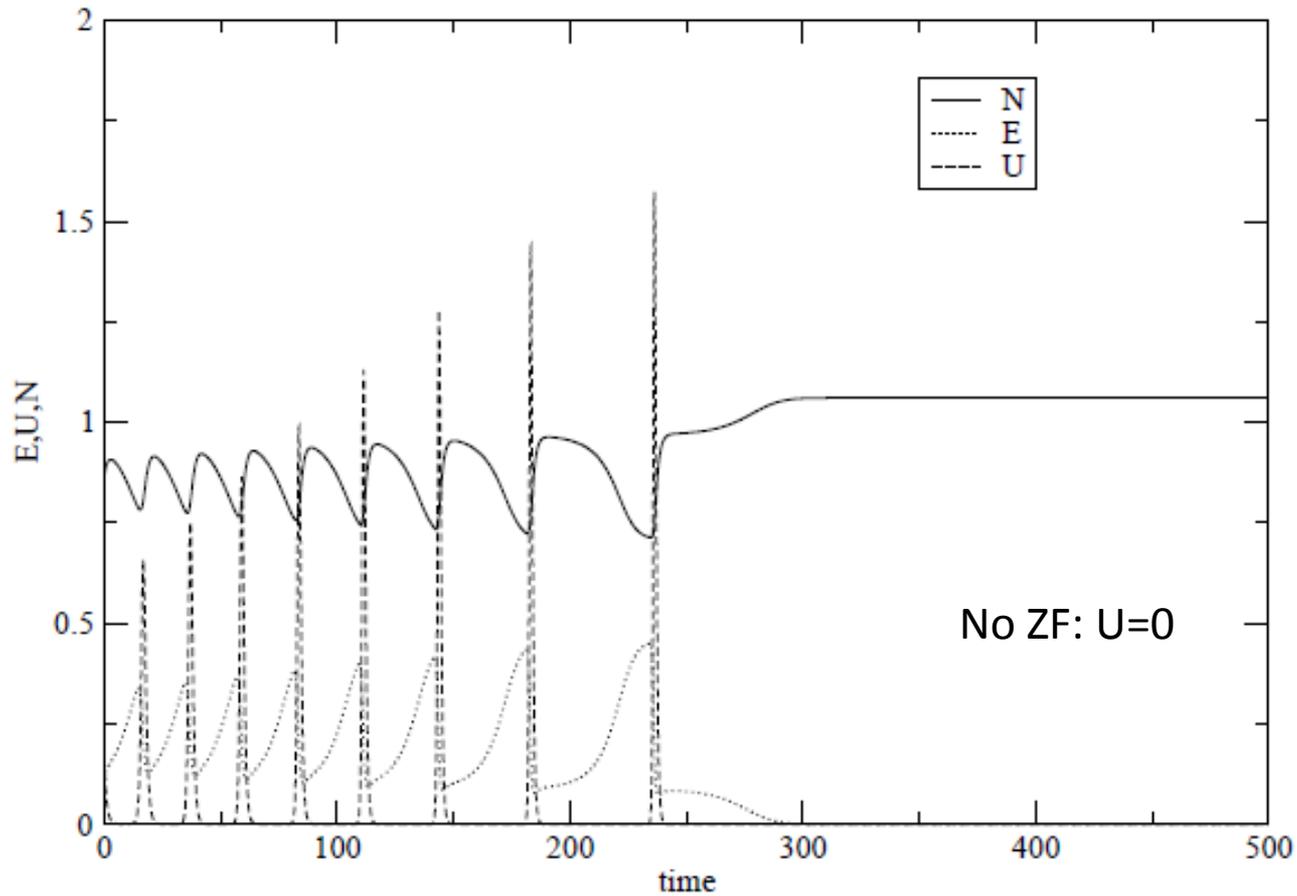
Unstable sequence, $q=0.47$

Unstable H \rightarrow unstable L \rightarrow stable T

Hopf bifurcation:
Stable T-mode \rightarrow
Stable limit cycle



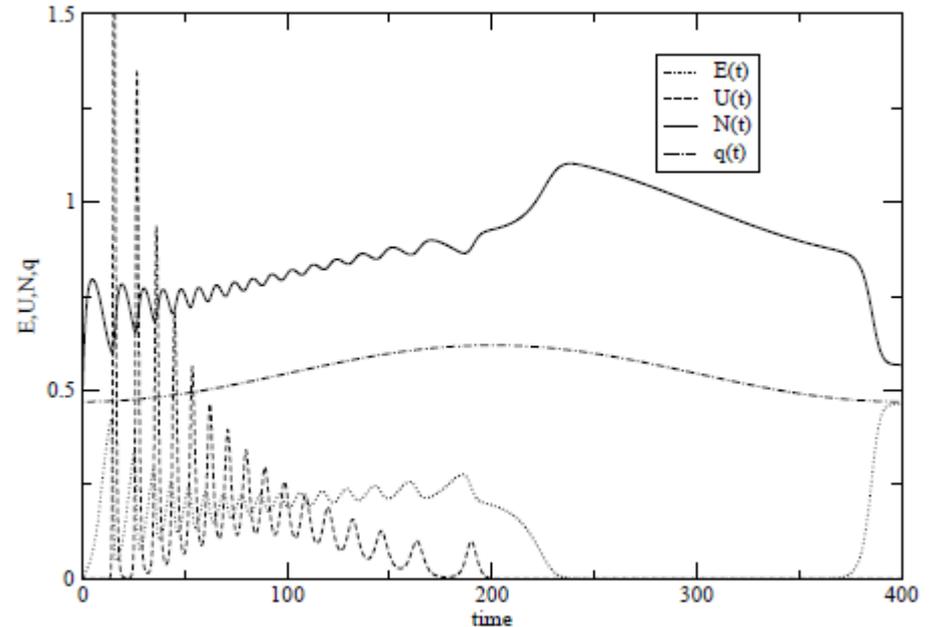
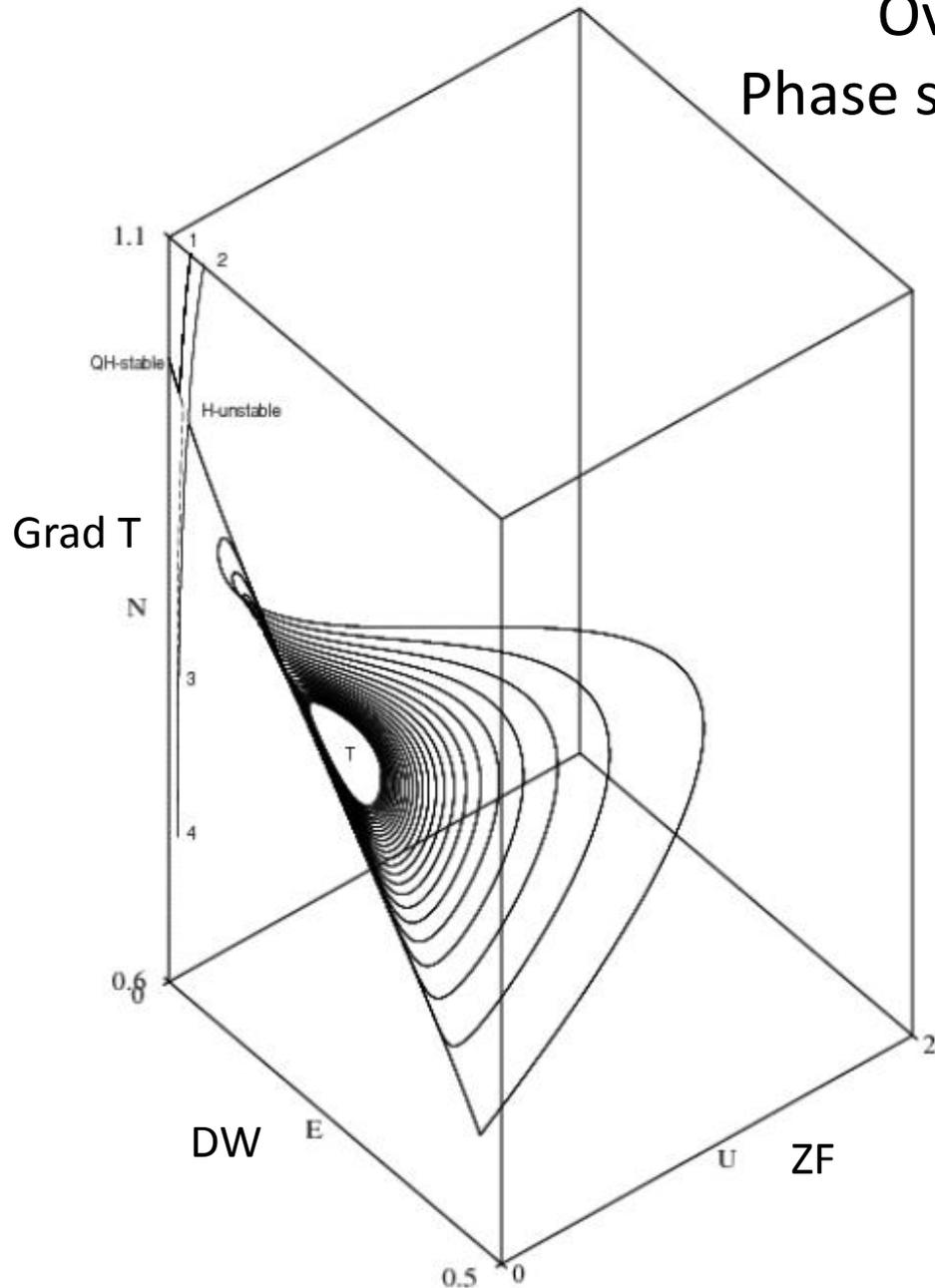
T \rightarrow QH transition



At $q=0.582$ limit cycle disappears

System transits to the QH mode (now the only stable fixed point)

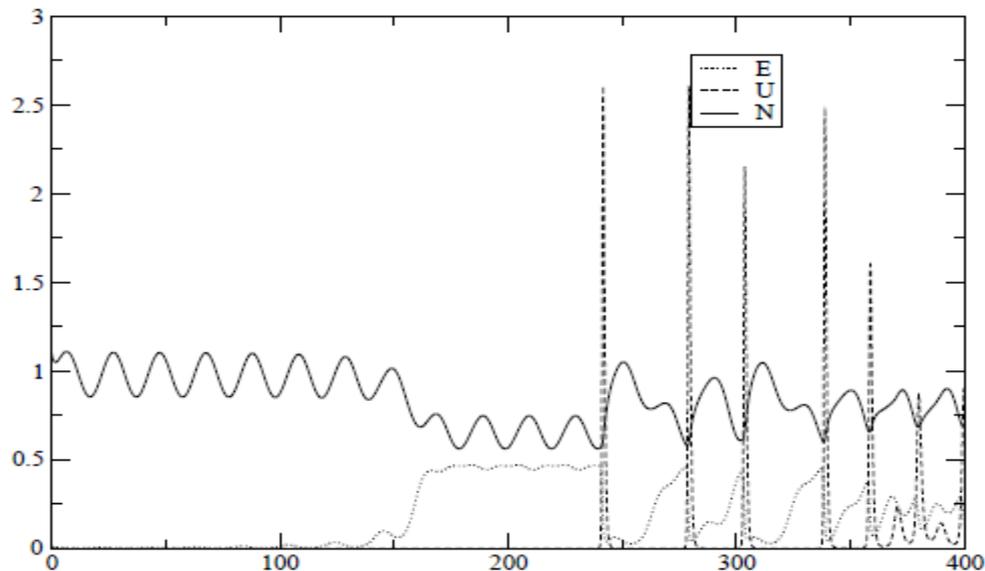
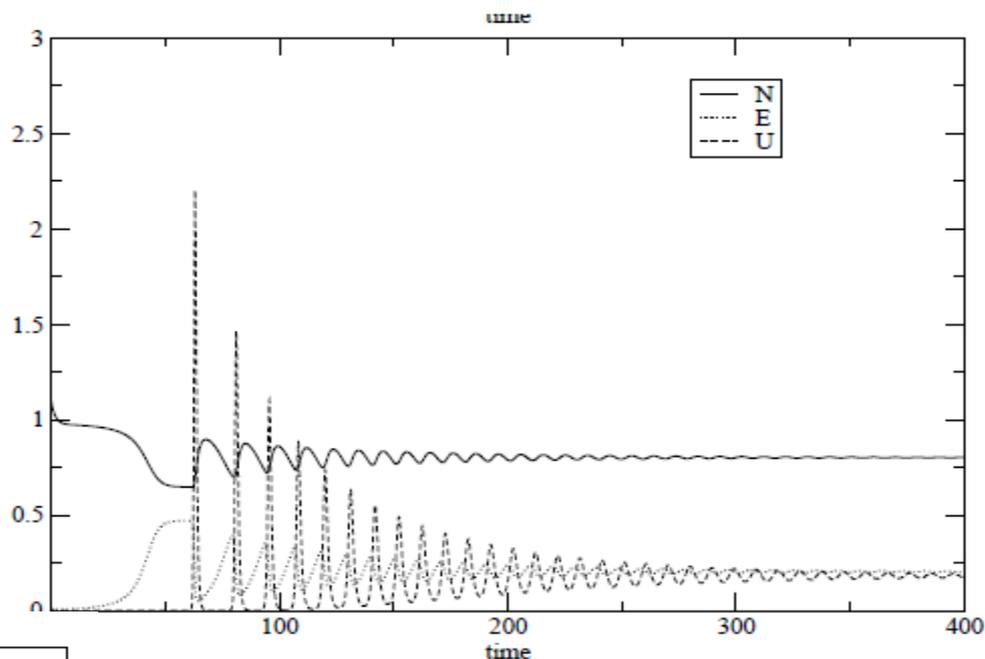
Overview of the Phase space of the system



- Asymmetry of forward and back transition
- Forward transition from L to QH transition requires finite ZF (temporarily)
- Back transition may occur on ZF=0 plane
- Weak hysteresis, $\sim 10\%$ in heating rate q , not robust, sensitive to initial conditions

Stabilization of meta-stable H-mode fixed point by heat source modulation

Underpowered (unstable) QH mode
Undergoes transition to stable oscillatory T-mode



Applying modulated (sinusoidal) $q(t)$ with the same average
Significantly delays transition

Conclusions

- role of phase coexistence in defining hysteresis in *local* two-field 1D model is classified
 - Maxwell rule governs the onset of the forward and back transitions which formally precludes *hysteresis*
 - the model predicts a close link between fueling depth and the width of the enhanced confinement region
- retaining pressure profile curvature (*some non-locality*)
 - backward transition occurs at the end point of the co-existence interval
 - ❖ ‘half-S-curve’ *hysteresis*
 - ❖ Softening L-H transition requirements
 - the pedestal partially decouples from the fueling depth and broadens
- internal fueling further lowers power requirements for L-H transition
 - core density build-up may somewhat increase the transition threshold
- studies of dynamical model indicate that hysteresis exists, but the basin of attraction for the H-mode shrinks rapidly with decreasing power
 - ZF generation is necessary in L→H transition but can be avoided in H→L transition
 - Power needed to maintain QH-mode can be lowered by modulating the heat source